Product data sheet
Characteristics

ATV320U15N4B
Variable speed drive, Altivar Machine ATV320, $1.5 \mathrm{~kW}, 380 \ldots 500 \mathrm{~V}, 3$ phases, book


| Discrete output type | Open collector DQ $+0 . .1 \mathrm{kHz} 30 \mathrm{~V}$ DC 100 mA Open collector DQ-0... 1 kHz 30 V DC 100 mA |
| :---: | :---: |
| Analogue input number | 3 |
| Analogue input type | Al1 voltage: $0 \ldots 10 \mathrm{~V}$ DC, impedance: 30 kOhm , resolution 10 bits AI2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm , resolution 10 bits Al3 current: $0 . . .20 \mathrm{~mA}$ (or $4-20 \mathrm{~mA}, \mathrm{x}-20 \mathrm{~mA}, 20-\mathrm{x} \mathrm{mA}$ or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits |
| Analogue output number | 1 |
| Analogue output type | Software-configurable current AQ1: $0 \ldots 20 \mathrm{~mA}$ impedance 800 Ohm, resolution 10 bits Software-configurable voltage AQ1: $0 \ldots 10 \mathrm{~V}$ DC impedance 470 Ohm, resolution 10 bits |
| Relay output type | Configurable relay logic R1A 1 NO electrical durability 100000 cycles Configurable relay logic R1B 1 NC electrical durability 100000 cycles Configurable relay logic R1C <br> Configurable relay logic R2A 1 NO electrical durability 100000 cycles Configurable relay logic R2C |
| Maximum switching current | ```Relay output R1A, R1B, R1C on resistive load, cos phi = 1:3 A at 250 V AC Relay output R1A, R1B, R1C on resistive load, cos phi =1:3 A at 30 V DC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi =0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms:2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1:5 A at 250 V AC Relay output R2A, R2C on resistive load, cos phi=1:5 A at 30 V DC``` |
| Minimum switching current | Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC |
| Method of access | Slave CANopen |
| 4 quadrant operation possible | True |
| Asynchronous motor control profile | Voltage/frequency ratio, 5 points <br> Flux vector control without sensor, standard <br> Voltage/frequency ratio - Energy Saving, quadratic U/f <br> Flux vector control without sensor - Energy Saving <br> Voltage/frequency ratio, 2 points |
| Synchronous motor control profile | Vector control without sensor |
| Maximum output frequency | 0.599 kHz |
| Transient overtorque | 170... 200 \% of nominal motor torque |
| Acceleration and deceleration ramps | Linear <br> U <br> S <br> CUS <br> Ramp switching <br> Acceleration/deceleration ramp adaptation <br> Acceleration/deceleration automatic stop with DC injection |
| Motor slip compensation | Automatic whatever the load <br> Adjustable 0... 300 \% <br> Not available in voltage/frequency ratio (2 or 5 points) |
| Switching frequency | 2... 16 kHz adjustable <br> $4 . . .16 \mathrm{kHz}$ with derating factor |
| Nominal switching frequency | 4 kHz |
| Braking to standstill | By DC injection |
| Brake chopper integrated | True |
| Line current | 6.5 A at 380 V (heavy duty) <br> 4.9 A at 500 V (heavy duty) |
| Maximum input current | 6.5 A |
| Maximum output voltage | 500 V |
| Apparent power | 4.2 kVA at 500 V (heavy duty) |
| Network frequency | $50 \ldots 60 \mathrm{~Hz}$ |
| Relative symmetric network frequency tolerance | 5 \% |
| Prospective line Isc | 5 kA |
| Base load current at high overload | 1.5 A |
| Power dissipation in W | Fan: 56.0 W at 380 V , switching frequency 4 kHz |
| With safety function Safely Limited Speed (SLS) | True |


| With safety function Safe brake <br> management (SBC/SBT) | False |
| :--- | :--- |
| With safety function Safe Operating <br> Stop (SOS) | False |
| With safety function Safe Position (SP) | False |
| With safety function Safe <br> programmable logic | False |
| With safety function Safe Speed <br> Monitor (SSM) | False |
| With safety function Safe Stop 1 (SS1) | True |
| With sft fct Safe Stop 2 (SS2) | False |
| With safety function Safe torque off <br> (STO) | True |
| With safety function Safely Limited | False |
| Position (SLP) | False |
| With safety function Safe Direction <br> (SDI) | Input phase breaks: drive <br> Orotection type <br>  <br> Overcurrent between output phases and earth: drive <br>  <br> Short-circuit brotection: drive <br> Thermal protection: drive phases: drive <br> WidthHeight 325.0 mm <br> Depth 245.0 mm <br> Net weight 2.5 kg |

## Environment

| Operating position | Vertical +/- 10 degree |
| :---: | :---: |
| Product certifications | CE <br> ATEX <br> NOM <br> GOST <br> EAC <br> RCM <br> KC |
| Marking | CE <br> ATEX <br> UL <br> CSA <br> EAC <br> RCM |
| Electromagnetic compatibility | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 <br> Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 <br> $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to IEC 61000-4-5 <br> Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 <br> Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Environmental class (during operation) | Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3 |
| Maximum acceleration under shock impact (during operation) | $150 \mathrm{~m} / \mathrm{s}^{2}$ at 11 ms |
| Maximum acceleration under vibrational stress (during operation) | $10 \mathrm{~m} / \mathrm{s}^{2}$ at $13 . . .200 \mathrm{~Hz}$ |
| Maximum deflection under vibratory load (during operation) | 1.5 mm at $2 \ldots 13 \mathrm{~Hz}$ |
| Permitted relative humidity (during operation) | Class 3K5 according to EN 60721-3 |
| Volume of cooling air | $9.4 \mathrm{~m} 3 / \mathrm{h}$ |
| Overvoltage category | III |
| Regulation loop | Adjustable PID regulator |
| Speed accuracy | +/-10\% of nominal slip 0.2 Tn to Tn |
|  |  |


| Pollution degree | 2 |
| :--- | :--- |
| Ambient air transport temperature | $-25 \ldots . .70^{\circ} \mathrm{C}$ |
| Ambient air temperature for operation | $-10 \ldots .50^{\circ} \mathrm{C}$ without derating |
|  | $50 \ldots . .60^{\circ} \mathrm{C}$ with derating factor |
| Ambient air temperature for storage | $-25 \ldots .0^{\circ} \mathrm{C}$ |
|  |  |
| Packing Units | PCE |
| Unit Type of Package 1 | 1 |
| Number of Units in Package 1 | 2.386 kg |
| Package 1 Weight | 8.2 cm |
| Package 1 Height | 27.5 cm |
| Package 1 width | 32 cm |
| Package 1 Length | P06 |
| Unit Type of Package 2 | 24 |
| Number of Units in Package 2 | 70.26 kg |
| Package 2 Weight | 80 cm |
| Package 2 Height | 80 cm |
| Package 2 width | 60 cm |
| Package 2 Length |  |

Offer Sustainability

| Sustainable offer status | Green Premium product |
| :--- | :--- |
| REACh Regulation | REACh Declaration |
| EU RoHS Directive | Pro-active compliance (Product out of EU RoHS legal scope) <br> EU RoHS Declaration |
| Mercury free | Yes |
| RoHS exemption information | Yes |
| China RoHS Regulation | China RoHS declaration |
| Environmental Disclosure | Product Environmental Profile |
| Circularity Profile | End of Life Information |
| WEEE | The product must be disposed on European Union markets following specific waste collection and <br> never end up in rubbish bins |
| California proposition 65 | WARNING: This product can expose you to chemicals including: Lead and lead compounds, which <br> is known to the State of California to cause cancer and birth defects or other reproductive harm. For <br> more information go to www.P65Warnings.ca.gov |
| Upgradeability | Upgraded components available $\quad$ ■ |

## Bottom, Right and Front View



(1) Minimum value corresponding to thermal constraints.
(2) Optional GV2 circuit-breaker

NOTE: The product overall height dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.) instead of 325 mm (12.80 in.)

(1) Ground screw (HS type 2-5x12)

## Diagram with Line Contactor

Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

(1) Line choke (if used)
(2) Fault relay contacts, for remote signaling of drive status

## Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.


(1) Analog output
(2) Analog inputs
(3) Reference potentiometer ( 10 kOhm maxi)
(4) Digital inputs

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.
Switch SW1 set to "Source" position and use of the output power supply for the DIs.

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Switch SW1 set to "Source" position and use of an external power supply for the DIs.


Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.


Switch SW1 set to "Sink Ext" position and use of an external power supply for the DIs.
ATV 320 ****B


## Derating Curves

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).


- $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ - Mounting type A, B and C
… $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$ - Mounting type $\mathrm{A}, \mathrm{B}$ and C
- $60^{\circ} \mathrm{C}\left(140^{\circ} \mathrm{F}\right)$ - Mounting type B and C

In: $\quad$ Nominal Drive Current
SF : Switching Frequency

